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BOARD DIPLOMA EXAMINATION, (C-09) OCT/NOV-2017

DME—SIXTH SEMESTER EXAMINATION

CAD/CAM

Time : 3 hours]

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[Total Marks : 80

PART—A 3×10=30

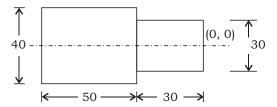
Instructions : (1) Answer **all** questions.

- (2) Each question carries **three** marks.
- (3) Answers should be brief and straight to the point and shall not exceed *five* simple sentences.
- **1.** Write the advantages of CAD.
- **2.** Write the types of output devices.
- **3.** Write the list of cursor control devices used in CAD systems.
- 4. Define an encoder. Give two examples.
- 5. Distinguish between NC and CNC.
- **6.** What is machining centre? Write the types of machining centre.
- **7.** Define word address format. Give an example of NC instruction (block) written in word address format.

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- 8. Explain briefly about canned cycle for turning.
- 9. Define flexible manufacturing system (FMS).
- **10.** Explain the function of coordinate measuring machine.

- Instructions : (1) Answer any five questions.
 - (2) Each question carries **ten** marks.
 - (3) Answers should be comprehensive and the criterion for valuation is the content but not the length of the answer.
- **11.** (a) How the computers and other peripheral devices share the information in a network?
 - (b) Explain briefly with a neat sketch various types of layout of LAN. 5+5
- 12. Explain MRP-I and MRP-II by using suitable block diagram.
- **13.** (*a*) Describe the working of an automatic tool changer with a sketch.
 - (b) Define tool magazine. Describe the working of tool magazine. 5+5
- 14. Explain manufacturing methodology on CNC machining.
- **15.** Write a part program for the component shown in the figure. The machining parameters are given below (dimensions are in mm) :



Cutting speed = 800 r.p.m. Feed = 200 mm/min Max. depth of cut = 3 mm

/3782 2 [Contd... www.ManaResults.co.in

- **16.** Explain briefly the linear and circular interpolation. Give one example for each.
- **17.** (*a*) Describe the main features of CNC, CMM with neat sketch for each.
 - (b) What are the advantages of CNC, CMM? 5+5
- 18. Write the classification of robots and their advantages.

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