

**Code No: 126AK****JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY HYDERABAD****B. Tech III Year II Semester Examinations, December - 2019****MICROPROCESSORS AND INTERFACING DEVICES****(Electrical and Electronics Engineering)****Time: 3 hours****Max. Marks: 75****Note:** This question paper contains two parts A and B.

Part A is compulsory which carries 25 marks. Answer all questions in Part A. Part B consists of 5 Units. Answer any one full question from each unit. Each question carries 10 marks and may have a, b, c as sub questions.

**PART - A****(25 Marks)**

- 1.a) List the advantages of memory segmentation. [2]
- b) What physical address is represented by 4000:561E? [3]
- c) How is 8255 configured if its control register contains 80<sub>H</sub>? [2]
- d) Explain the differences between static and dynamic memories. [3]
- e) What is the function of Stack and stack register? [2]
- f) Give important IEEE-488 standards. [3]
- g) Draw the hardware diagram to acquire data using 8-bit ADC. [2]
- h) Compare PUSH and POP instructions in 8086. [3]
- i) Name the addressing modes of 8086. [2]
- j) What is the need of timers in 8051? [3]

**PART - B****(50 Marks)**

- 2.a) Draw the internal register diagram of 8086 and explain the function of each register.
- b) Explain the function of following pins of 8086. [5+5]
  - i)  $\overline{DT/\overline{R}}$
  - ii)  $\overline{READY}$
  - iii)  $\overline{INTA}$

**OR**

- 3.a) Discuss the function of maximum mode control bus signals and explain how they are produced.
- b) Explain the following pins of 8086. [5+5]
  - (i)  $\overline{MN/\overline{MX}}$  (ii)  $\overline{TEST}$  (iii)  $\overline{BHE}$  (iv)  $\overline{DEN}$
- 4.a) What are assembler directives and explain the following assembler directives.
  - i) ASSUME (ii) SEGMENT (iii) DB (iv) PUBLIC
- b) Write an Assembly Language Program to sort the numbers in ascending order using bubble sort. [5+5]

**OR**

- 5.a) Explain the instructions related to arithmetic and logical shift with an examples.
- b) Write an 8086 program to add two 16 bit numbers in CX and DX and store the result in location 0500H addressed by DL. [5+5]

6.a) Sketch and explain the interface of PIC 8259 to the 8086 microprocessor in minimum mode. Write an assembly language program.

b) Discuss the Asynchronous and synchronous data transfer schemes. [5+5]

**OR**

7.a) Explain the interfacing of stepper motor to the 8086 MP with Assembly Language Program.

b) Explain D/A and A/D interfacing done by 8086 with an application. [5+5]

8.a) What is the need for conversion of TTL to RS232C. With the help of diagram explain the Conversion.

b) Explain the need of serial data transfer schemes. [5+5]

**OR**

9.a) With a block diagram explain the architecture of USART.

b) Discuss the mode instruction format of 8251 for synchronous and asynchronous mode of operation. [5+5]

10.a) Explain SCON register programming in 8051.

b) Write a program to multiply the data in RAM location 3A<sub>H</sub> by the number 11<sub>H</sub>. Put the result in R<sub>4</sub> and R<sub>5</sub> registers. [5+5]

**OR**

11.a) Write a program to double the number in register R<sub>2</sub> and put the result in R<sub>3</sub> and R<sub>4</sub> of 8051.

b) What are the addressing modes supported in 8051? Give examples. [5+5]

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