PART - A

		(25 Marks)
1.a)	What is maximum Unambiguous range?	[2]
b)	List the applications of radar.	[3]
c)	What is Doppler effect?	[2]
d)	List the applications of CW radar	[3]
e)	What is need of delay line canceller	[2]
f)	What is blind speeds?	[3]
g)	Mention the types of tracking	[2]
h)	What is meant by tracking in range?	[3]
i)	What is matched filter?	[2]
j)	List the types of radar receivers.	[3]

PART - B

		50 Marks)	
2.a) b)	Draw and explain the simple radar system with a neat block diagram. Derive the radar range equation. OR	[5+5]	
2	-		
3.a)	Explain the significance Radar cross section in range equation.		
b)	Derive an equation for probability of false alarm.	[5+5]	
4	Write a note on the following:		
4.	Write a note on the following:		
	a) FM-CW altimeter b) CW radar.	[5+5]	
	OR		
5.a)	Explain the working principle of multiple frequency CW radar.		
b)	What are the bandwidth requirements for a receiver?	[5+5]	
0)	what are the bandwidth requirements for a receiver?	[3+3]	
6.a)	Explain the working principle and function of each block of power	amplifier	
)	transmitter in MTI Radar?	r	
b)	Explain the function of pulse Doppler radar and how it is different from simple p	ulse radar?	
0)	Explain the function of pulse Dopplet fudul and now it is different from simple p	[5+5]	
	OR		
7.a)	What is an A-scope display? How it generates butterfly effect in MTI Radar system?		
, .u)	in a bour i boope aspage in or a generates buttering eneet in with radius syste		

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Time: 3 hours Note: This question paper contains two parts A and B.

Part A is compulsory which carries 25 marks. Answer all questions in Part A. Part B consists of 5 Units. Answer any one full question from each unit. Each question carries 10 marks and may have a, b, c as sub questions.

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY HYDERABAD B. Tech IV Year II Semester Examinations, May - 2019 **RADAR SYSTEMS**

(Electronics and Communication Engineering)

b)

Explain the limitations of MTI Radar.

Code No: 128EA



Max. Marks: 75

[5+5]

(50 Marks)

8.a)	Briefly explain the various tracking techniques of radar.	
b)	Explain the working of one-coordinate amplitude comparison mono pulse radar.	[5+5]
	OR	
9.a)	Explain the function of sequential lobe tracking.	
b)	Explain the working of phase comparison mono pulse radar.	[5+5]
10.a)	Explain the function of Balanced duplexer.	
b)	Explain the designing criteria of a Matched filter receiver.	[5+5]
	OR	
11.a)	Derive the effective noise temperature of N-antenna system.	
b)	Explain the working principle of Branch –type duplexer.	[5+5]

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